

## 1 Competition: Clause Sharing Selection Heuristic (3(+7) Points)

Manipulate Mallob’s clause sharing by modifying the class `ClausePrefilter` (see below), whose method `prefilterClause` is called whenever a solver thread produces a clause that passes a number of basic checks. The method can return `false` to completely drop a clause; if the method returns `true`, the calling solver thread will subsequently attempt to write the clause to an export buffer. You can change a (non unit) clause’s priority by manipulating its LBD value to make it more or less likely that a clause “survives” subsequent selection stages and is shared successfully. For a clause of length  $\ell \geq 2$ , LBD values of 2 (“best”) through  $\ell$  (“worst”) are valid. If needed, you may perform precomputations and access the formula in the body of `notifyFormula()`.

You get 3 points for submitting a functional version of `clause_prefilter.hpp` with some non-trivial change. The submissions that result in the best performance with a Kissat portfolio at 64 cores on diverse benchmarks get up to 7/5/3 additional points. We will, in particular, set the non-default parameters `-lbdpi=1 -lbdpo=1 -pbbm=1` to consistently prioritize clauses by “LBD” first and by clause length second (i.e., as a tiebreaker only) and `-rlbd=1 -ilbd=0` to reset each incoming clause’s LBD value to  $\ell$  before a solver thread imports it.

**Mallob version to use:** <https://github.com/domschrei/mallob/tree/experimental>

— `ClausePrefilter`: see `src/app/sat/sharing/filter/clause_prefilter.hpp`

Contact Dominik ([dominik.schreiber@kit.edu](mailto:dominik.schreiber@kit.edu)) in case of technical questions or issues.

## 2 Parallel Resolution (3 + 3 Points)

Consider a parallel setup with  $p$  resolution procedures in a “bulk synchronous parallel” (BSP) model: Each procedure performs a single resolution step; then, all resolvents are shared across all procedures. This is repeated until the empty clause is found.

- Provide an unsatisfiable CNF formula where the above setup *can* speed up the derivation of the empty clause by a factor of  $p/\log p$  (or better) compared to the shortest sequential resolution order.
- Provide an unsatisfiable CNF formula where the derivation of the empty clause can only ever be sped up by a factor of  $1 + \varepsilon$  (where  $0 \leq \varepsilon \ll 1$ ) compared to the shortest sequential resolution order.

## 3 VBS and Speedups (4 + 6 Points)

Analyze the results of the 2024 SAT Competition.

- Compute a VBS of all sequential main track solvers. Compare its performance to the best cloud track solver in the competition. Interpret the results, also considering any peculiar instance families.
- Compute the geometric mean and median speedup of each parallel track solver relative to the best performing sequential solver `kissat-sc2024`, only considering instances which both the sequential solver *and* the parallel solver were able to solve. Then do the same while considering *all* instances solved by the parallel solver – “generously” attributing a running time of 5000s to each such instance that the sequential solver did not solve. Interpret and compare the results.

**Competition results:** [https://satcompetition.github.io/2024/downloads/detailed\\_results.zip](https://satcompetition.github.io/2024/downloads/detailed_results.zip)

**Benchmark meta data:** <https://satcompetition.github.io/2024/downloads/meta.csv>

## 4 Clause Filtering in Distributed SAT (5 Points)

Distributed clause-sharing solvers like MALLOBSAT filter a repeated clause based on *exact syntactical equivalence* (i.e., if a clause  $c$  is shared successfully, then clause  $c$  will be blocked for some period). Find a way to generalize this approach to *subsumed* clauses, i.e., if clause  $c$  is shared, then all clauses  $c' \supseteq c$  are blocked for some period. Provide a rough analysis of the running time complexity and the memory footprint of your approach.